Lukas Pirl

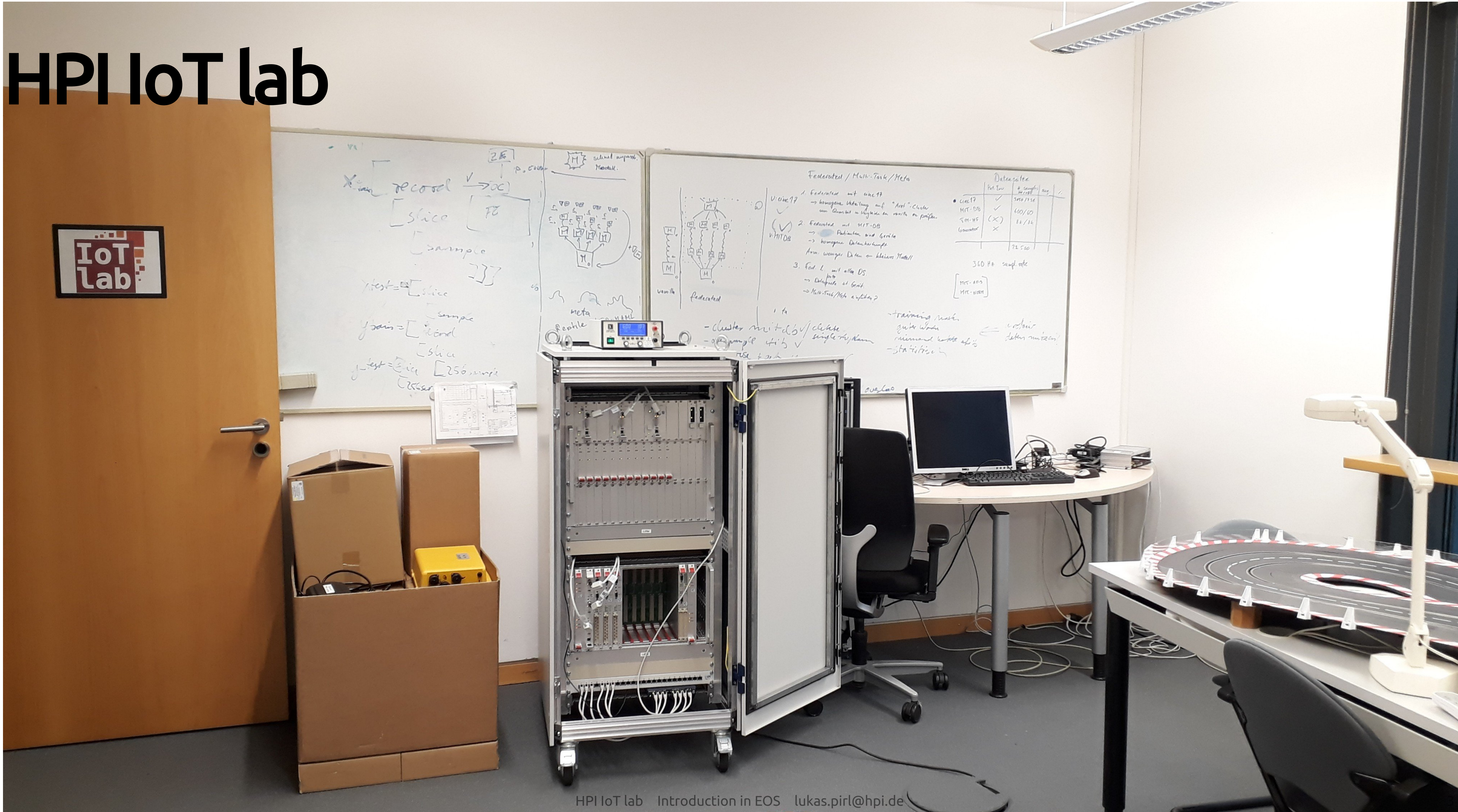
Introduction of IoT Lab in Lecture on Embedded Operating Systems

Professorship for Operating Systems and Middleware of Prof. Andreas Polze

Hasso Plattner Institute, University of Potsdam

HPI IoT lab

HPI IoT lab



HPI IoT lab

workshop

general tools

soldering

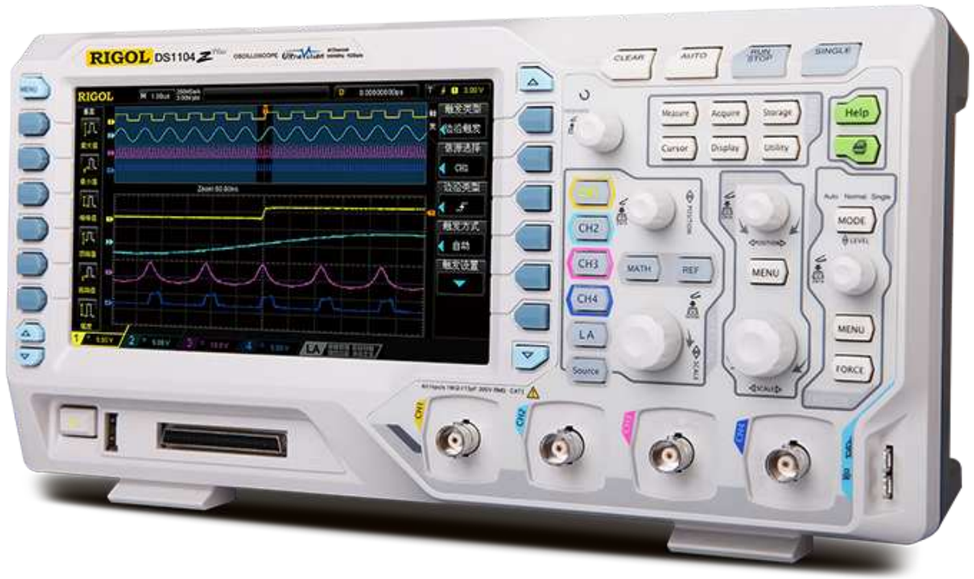
electronics components

bulk & DIY cables, connectors, etc.

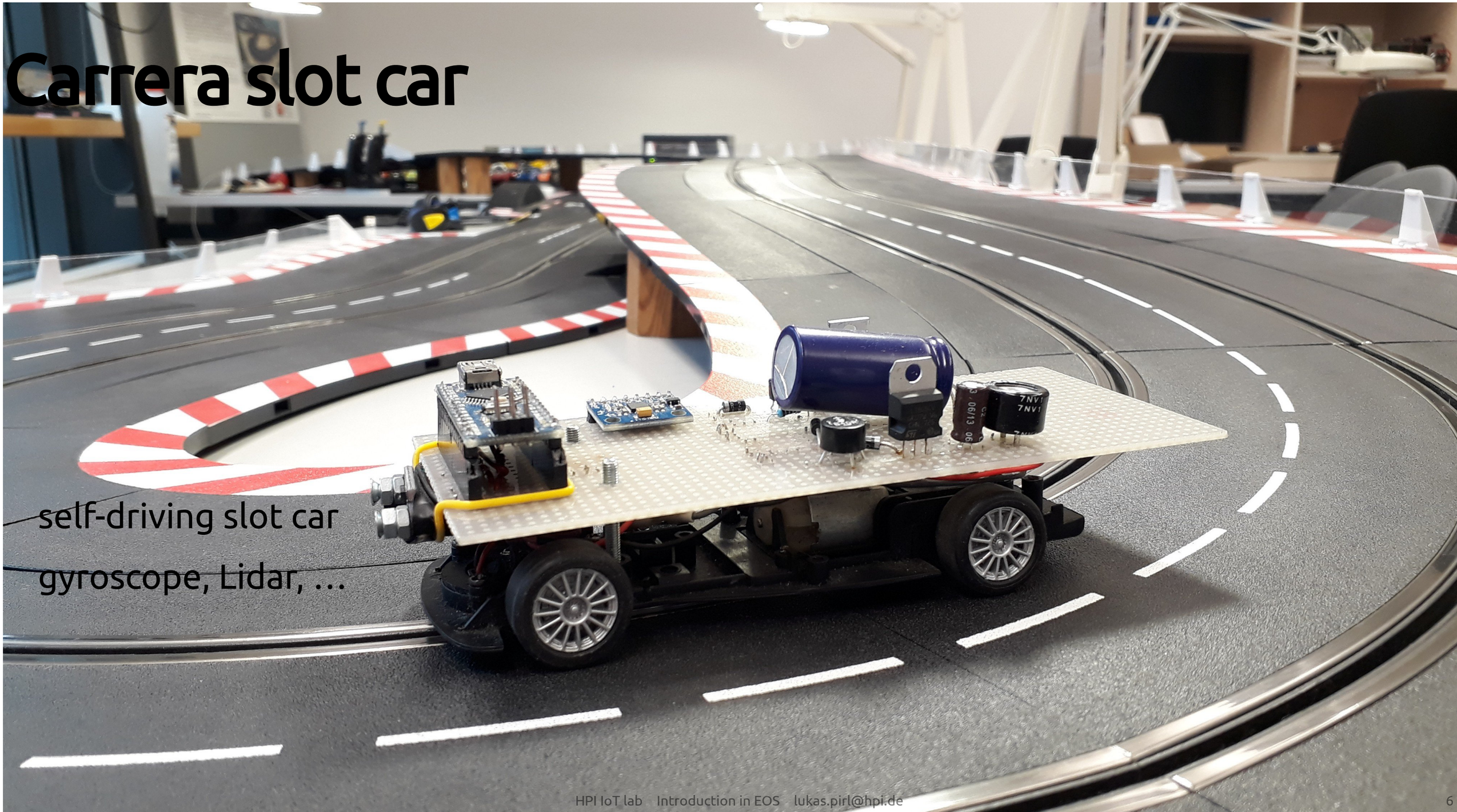
power supply

measurement

…



Carrera slot car



self-driving slot car

gyroscope, Lidar, …

Carrera slot car

custom PCBs

Björn Daase

Leon Matthes

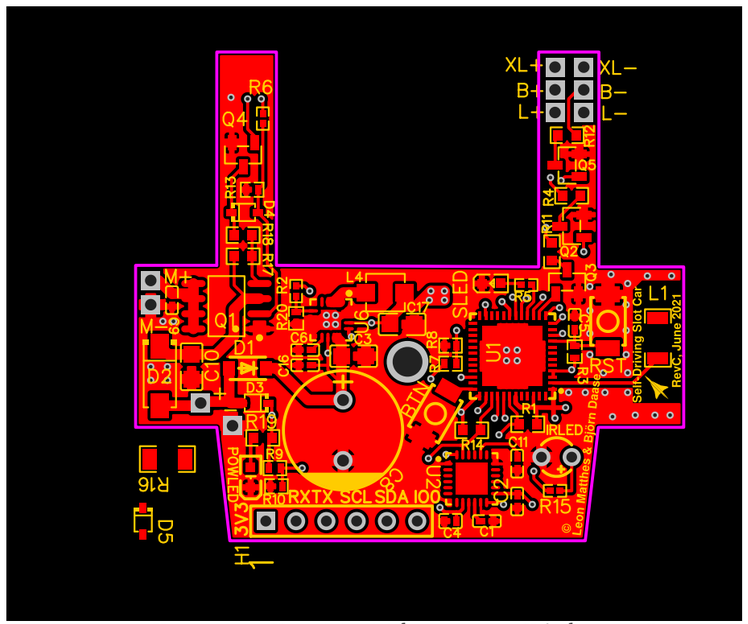
Carrera slot car

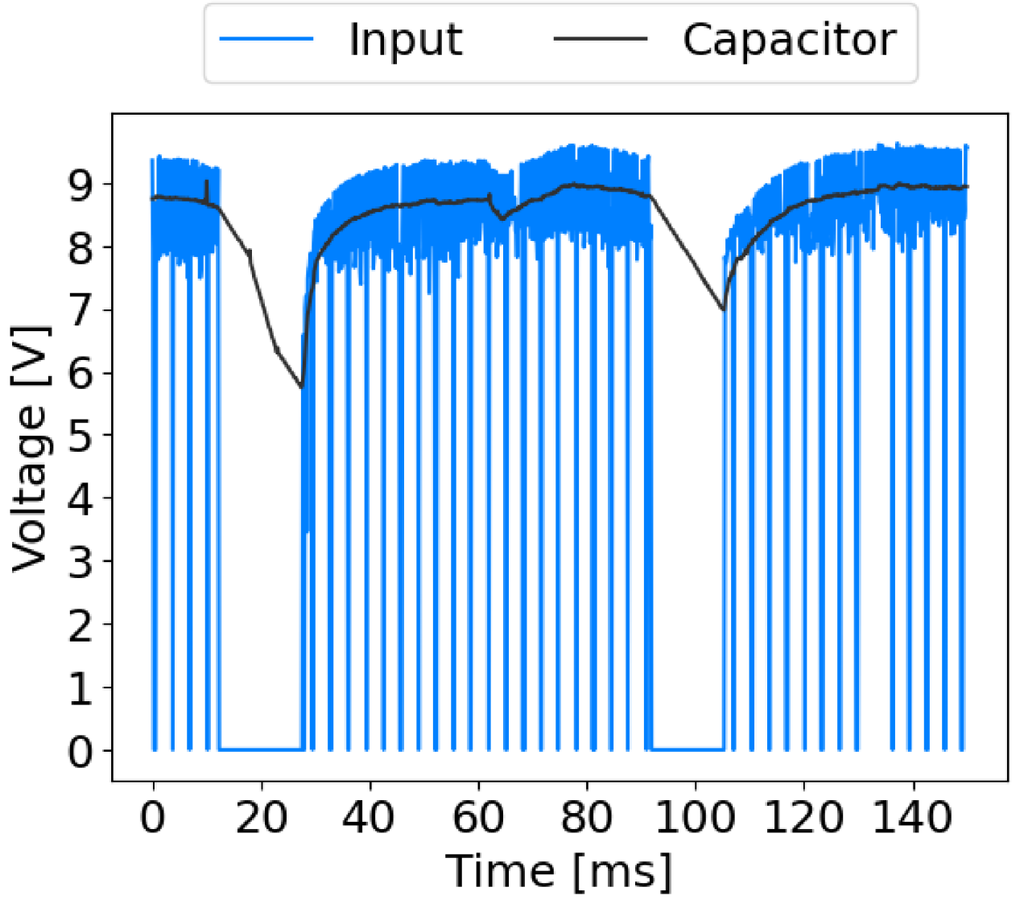
challenges

unusual power supply characteristics

remote/mobile debugging

PCB design





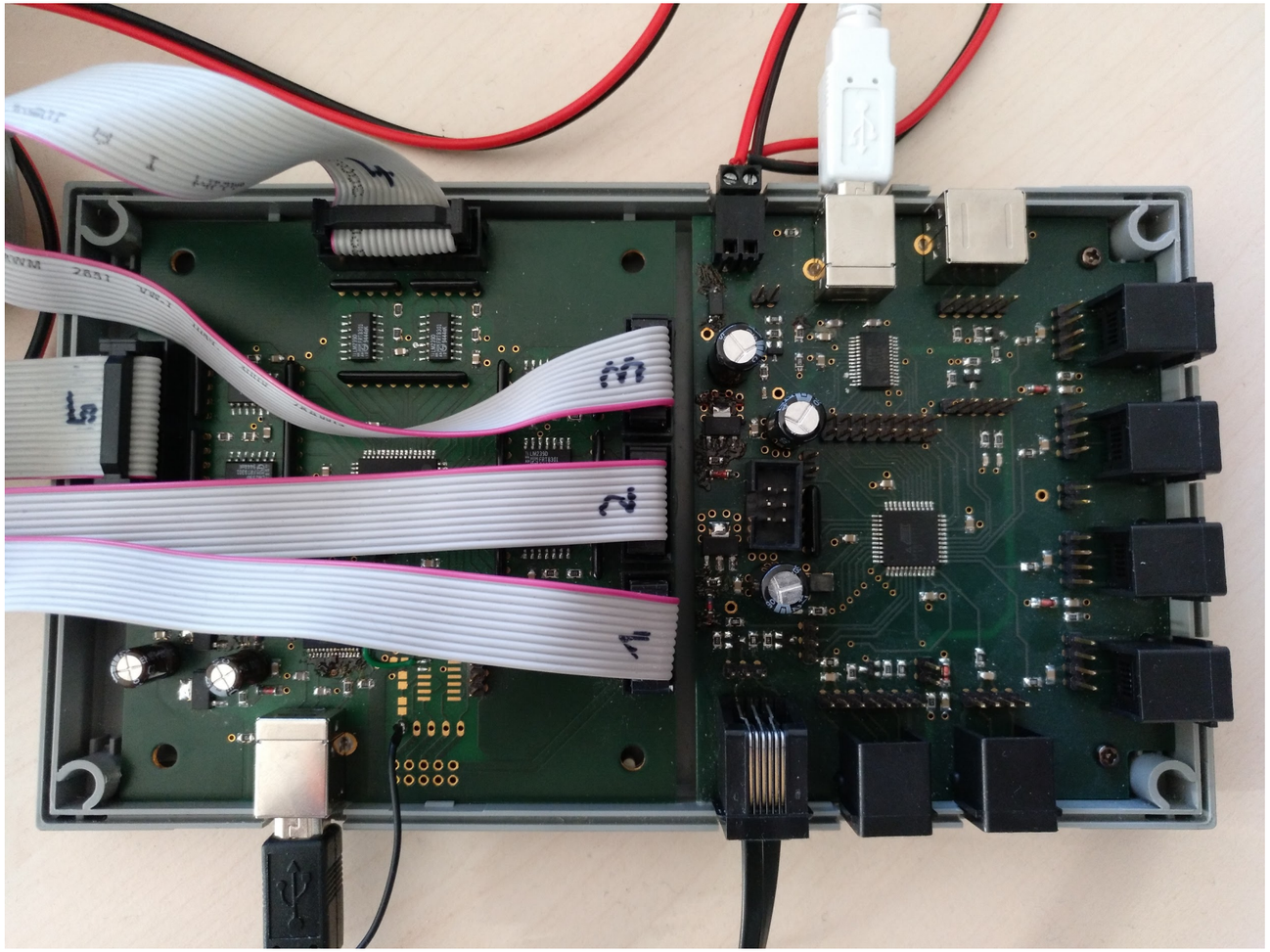
Daase, B., Matthes, L., Pirl, L., & Wenzel, L. Observing a Moving Target – Reliable Transmission of Debug Logs from Embedded Mobile Devices.

Carrera sensor & actuator board

working with the digital protocol

firmware level

e.g., prevent overtaking the safety car



single-board computers

distributed computing

energy-aware computing

heterogeneous computing

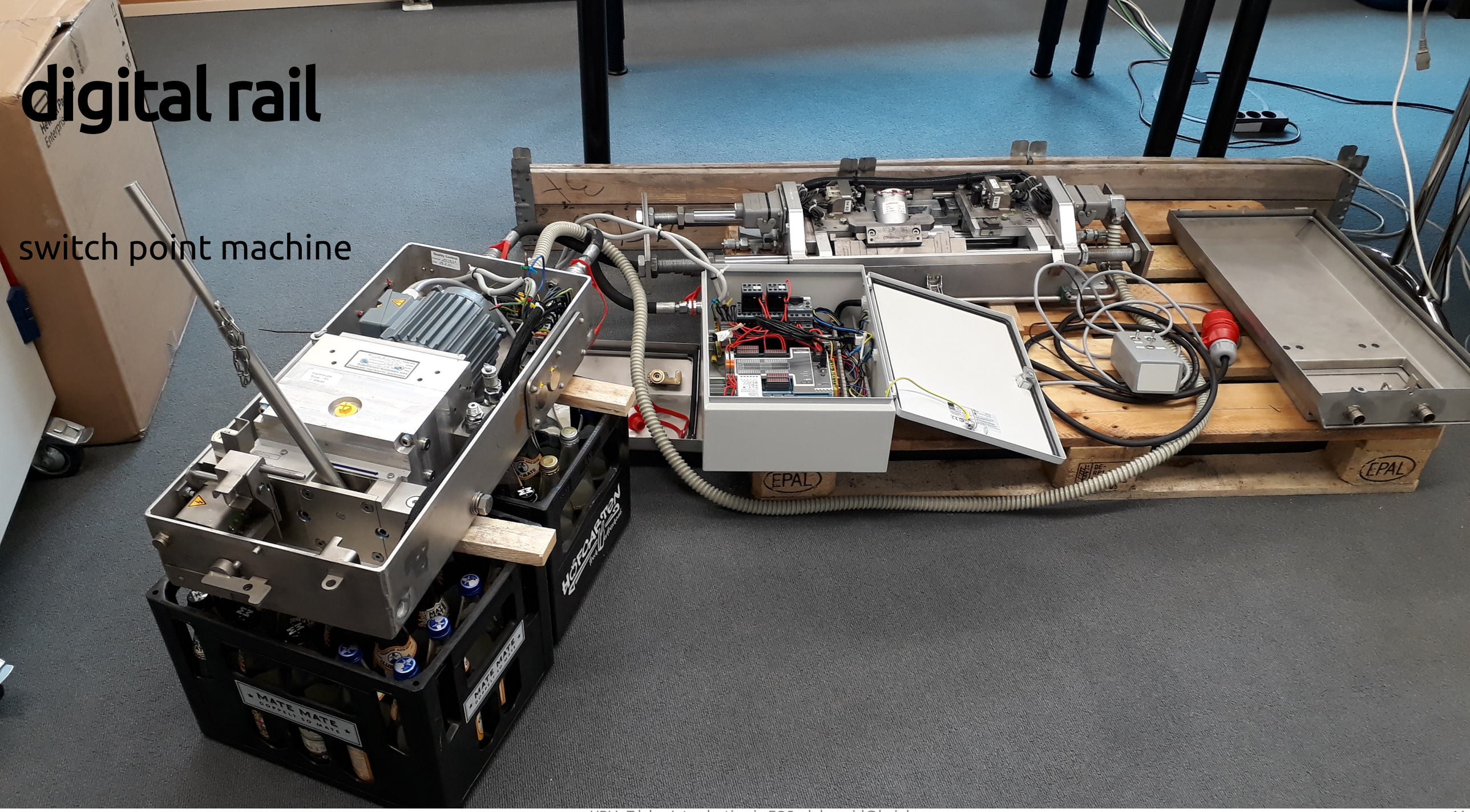
(GP)GPU, big.LITTLE, …

list of experiment hardware

https://osm.hpi.de/iot-lab/docs/hardware/generated-overview-of-experiment-hardware-list.html

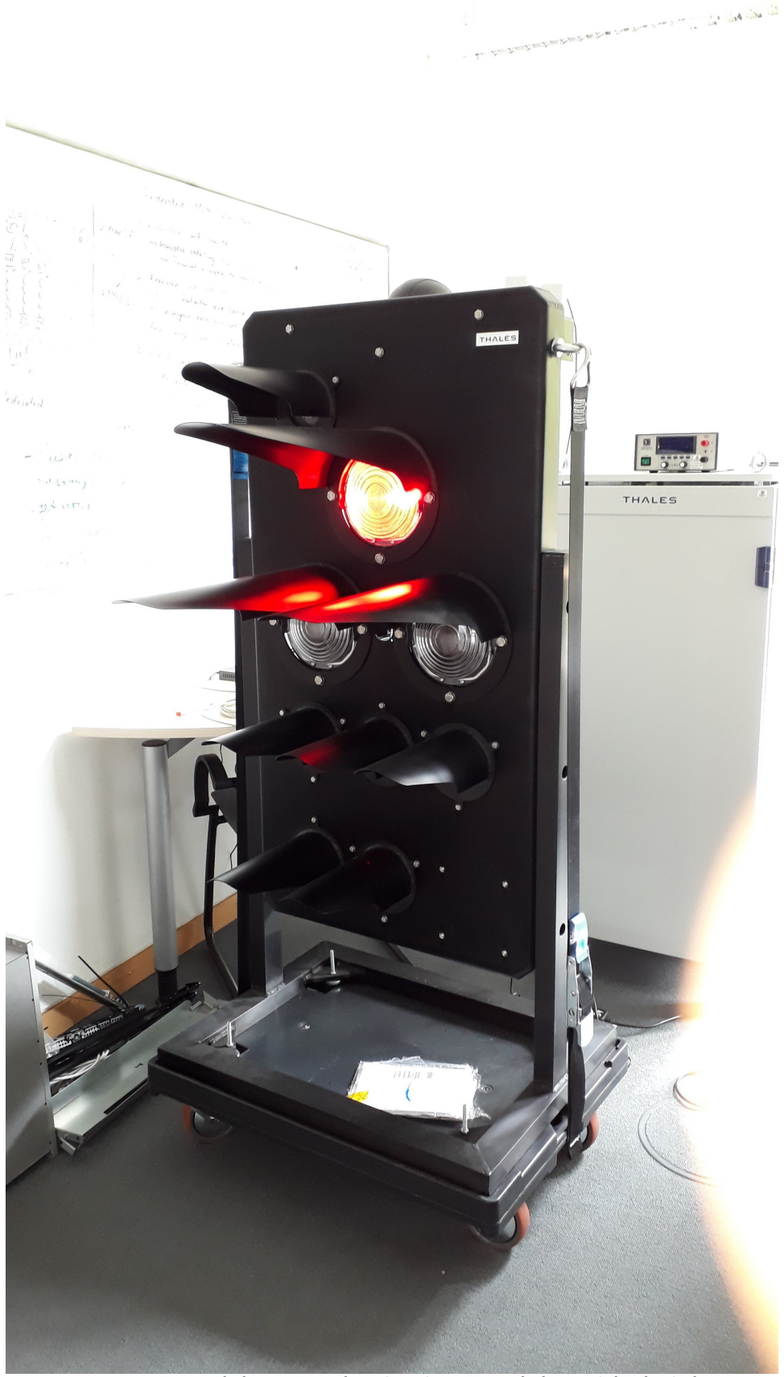
digital rail

switch point machine



digital rail

color light signal (Ks)




digital rail
30
Betreten der
Bahnanlagen
verboten

digital rail

model-generated code counts axles and controls signal

digital rail

DRSS

Digital Rail Summer School

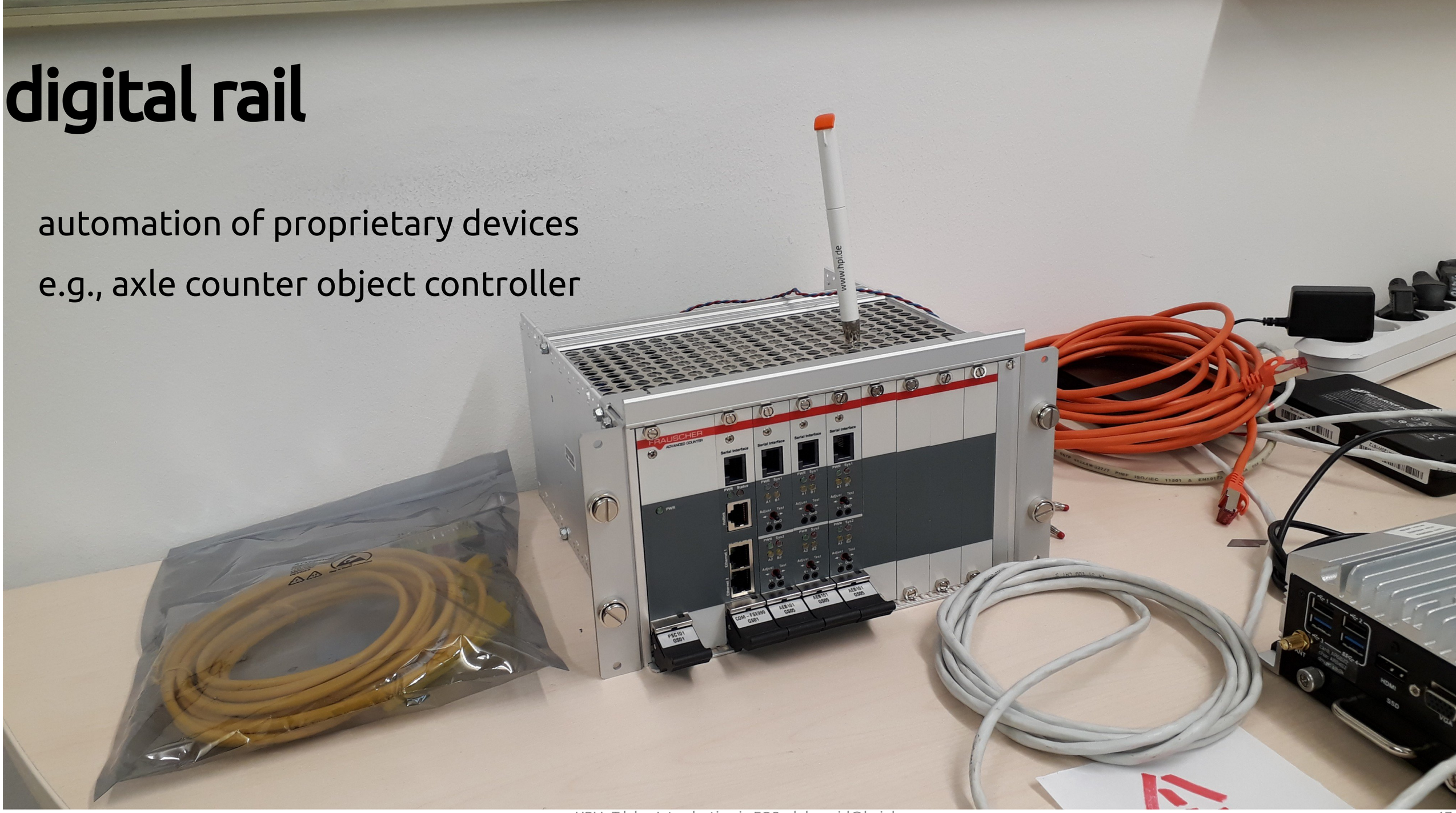
https://hpi.de/drss

DRSS 2021 already done, join 2022! :)

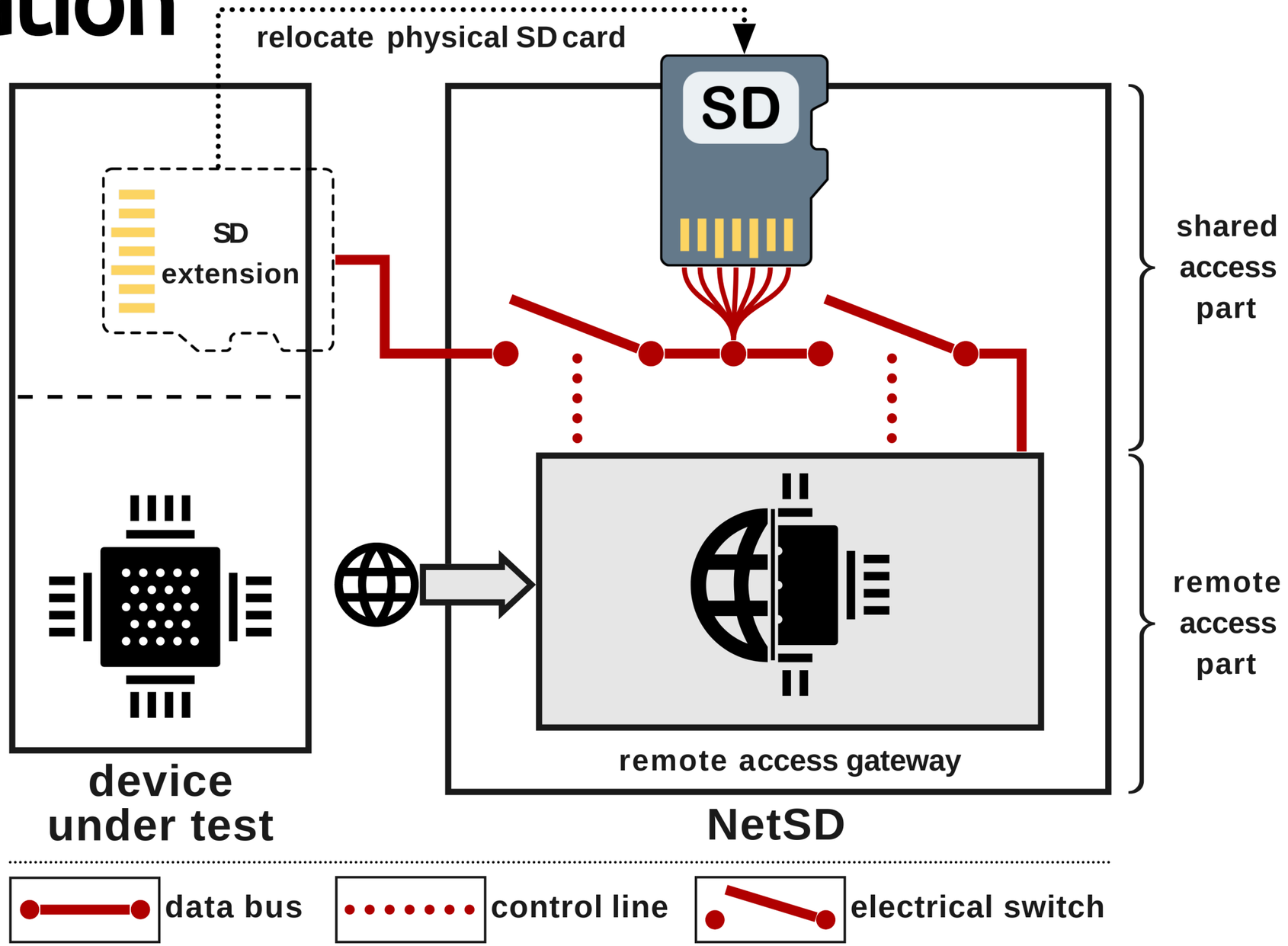
digital rail

automation of proprietary devices

e.g., axle counter object controller

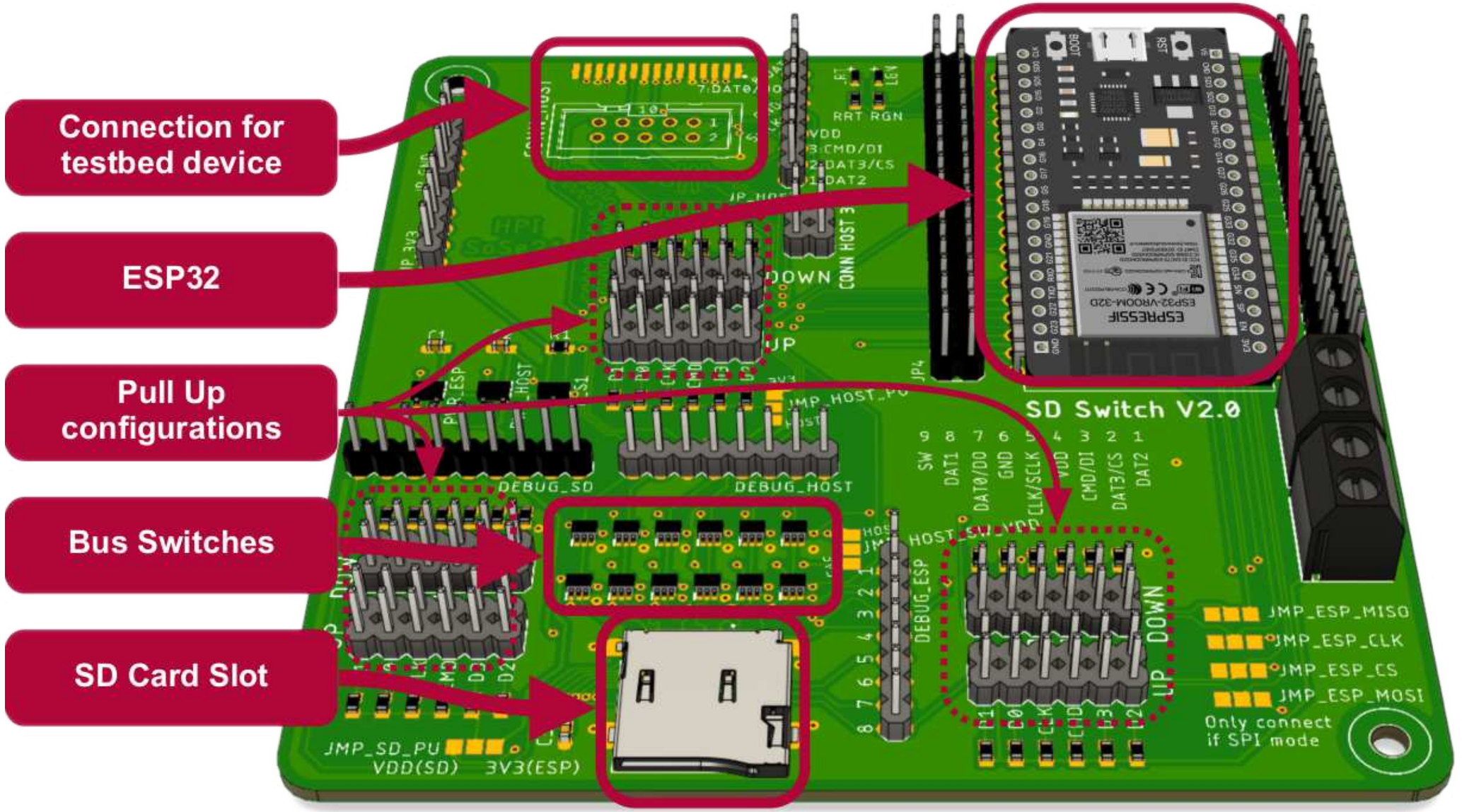


testbed automation



Schröter, V., Boockmeyer, A., & Pirl, L.
NetSD: Remote Access to Integrated
SD Cards of Embedded Devices.

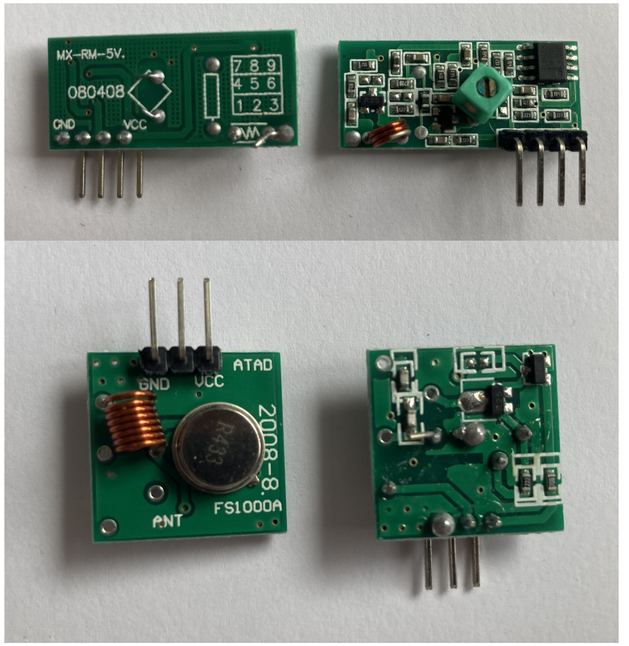
testbed automation

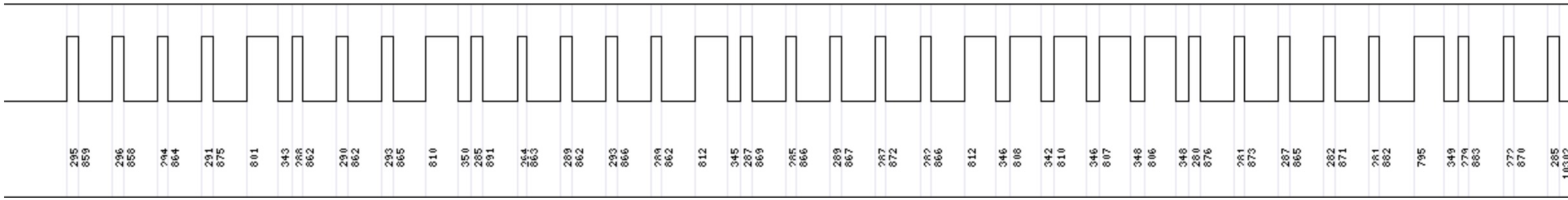


Valentin Schröter
Tobias Zagorni

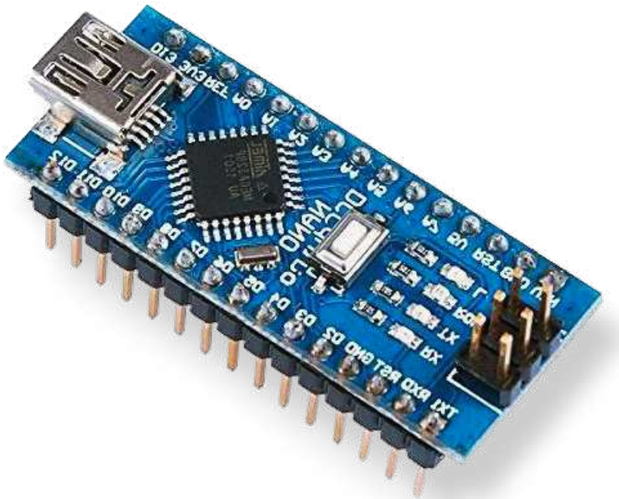
testbed automation

reverse engineering of switchable power sockets



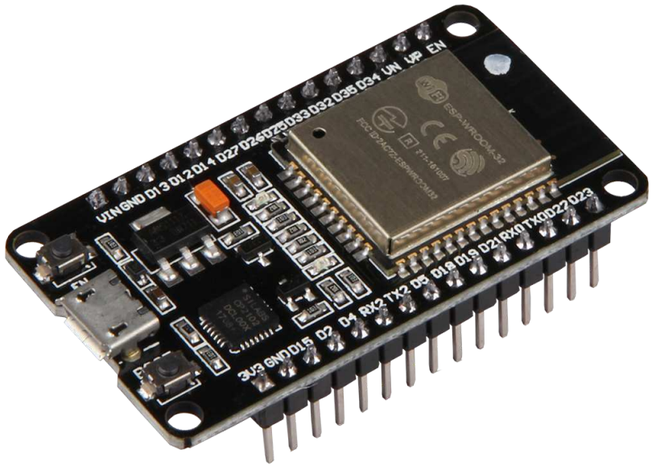


embedded devices & OS



devices

- Arduino
- ESP32
- Beckhoff SPS
- Lego
- Fischertechnik
- … *open to suggestions!* :)
  - incl. designing own PCBs



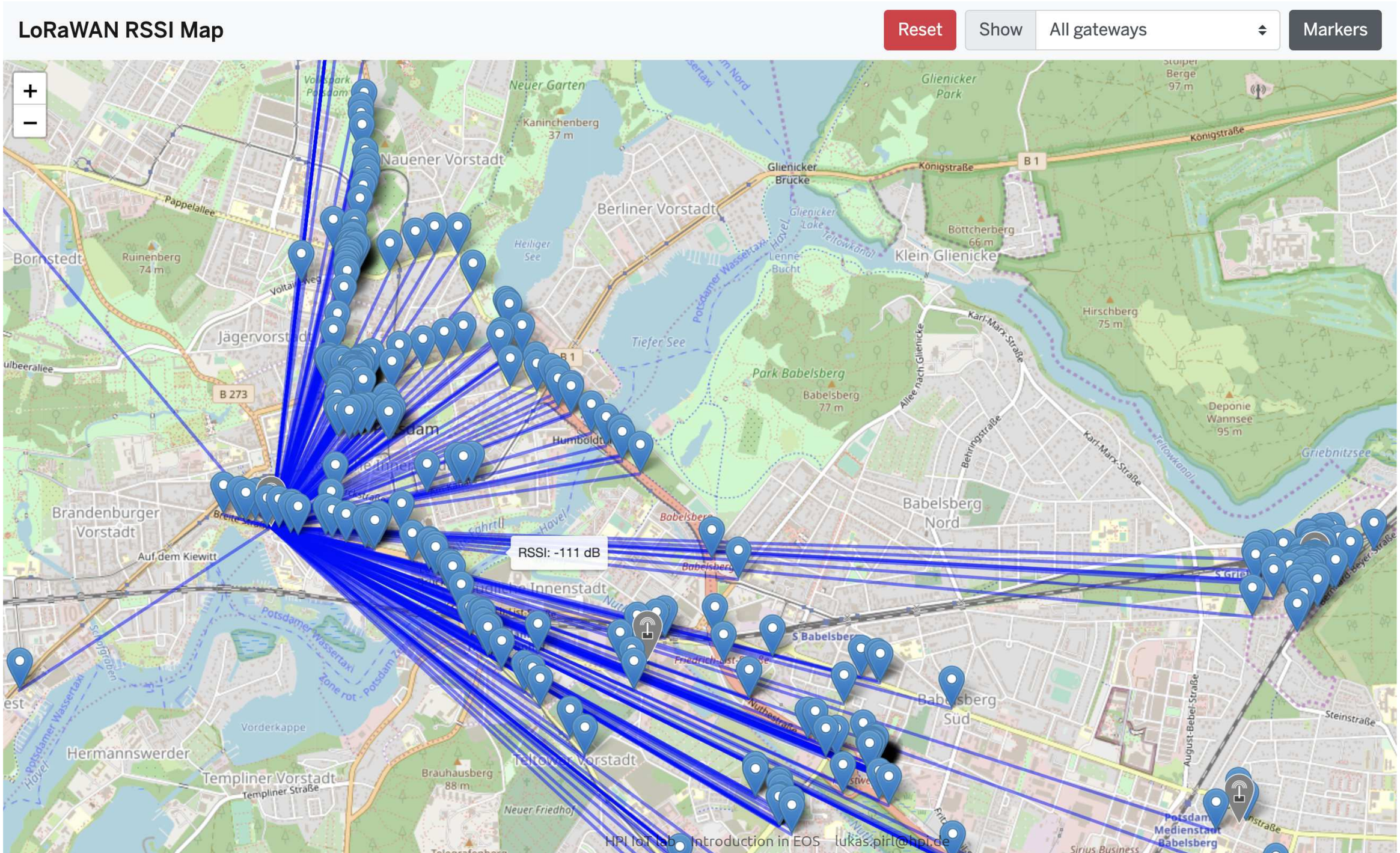
operating systems

- RIOT, *RTOS, OpenWRT, embedded Linux, Contiki, Android, …

radio technology

LoRa-WAN

SDR


LoRaWAN RSSI Map
Reset
Show
All gateways
Markers
RSSI: -111 dB
Neuer Garten
Kaninchenberg
37 m
Nauener Vorstadt
Glienicker Brücke
Königstraße
B 1
Berliner Vorstadt
Glienicker Park
Stolper Berge
97 m
Böttcherberg
66 m
Klein Glienicke
Hirschberg
75 m
Deponie Wannsee
95 m
Griebnitzsee
Pappelallee
Ruinenberg
74 m
Bornstedt
Jägervorstadt
B 273
Tiefer See
Heiliger See
Park Babelsberg
Babelsberg
77 m
Karl-Marx-Straße
Babelsberg Nord
Brandenburger Vorstadt
Auf dem Kiewitt
Innenstadt
Babelsberg Süd
Hermannswerder
Vorderkappe
Templiner Vorstadt
Templiner Straße
Brauhausberg
88 m
Neuer Friedhof
Potsdamer Wassertaxi
Havel
Steinstraße
August-Bebel-Straße
Potsdam Medienstadt Babelsberg

radio technology

IEEE 802.11p

Rail2X

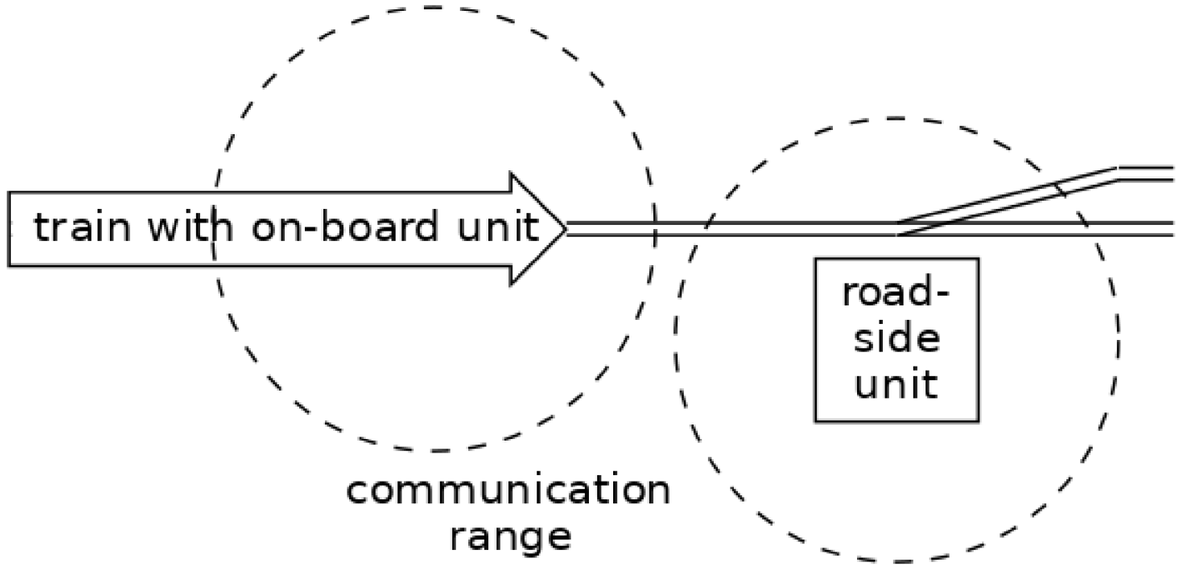
Vehicle-to-X communication (V2X) for railways (Rail2X)

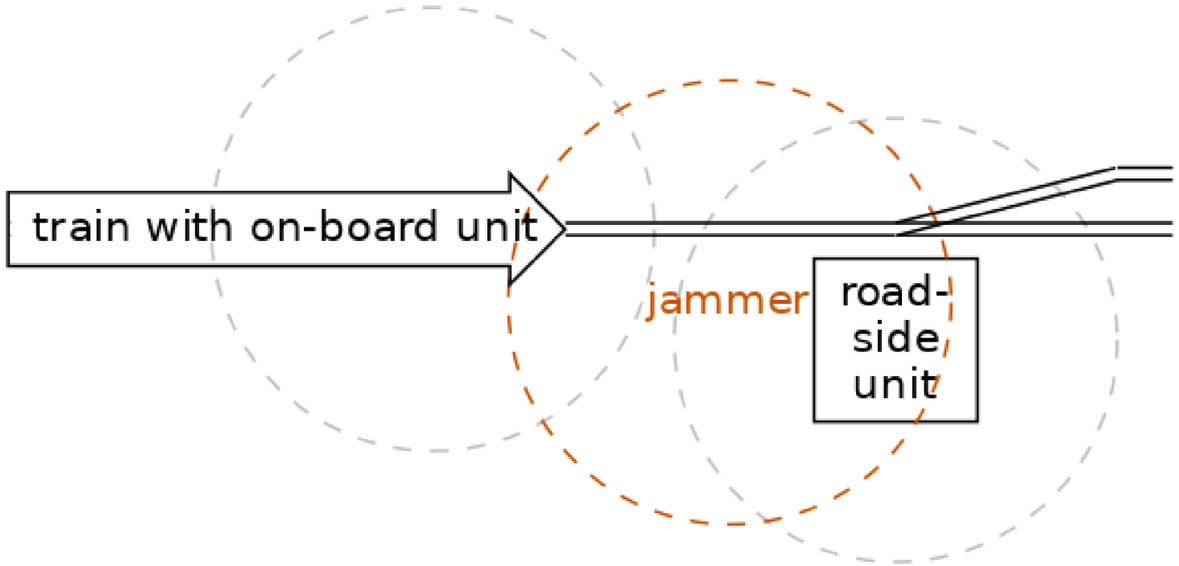
- smart mobility through interconnection of vehicles & infrastructure
- analogue: Car2X, Ship2X, Airplane2X

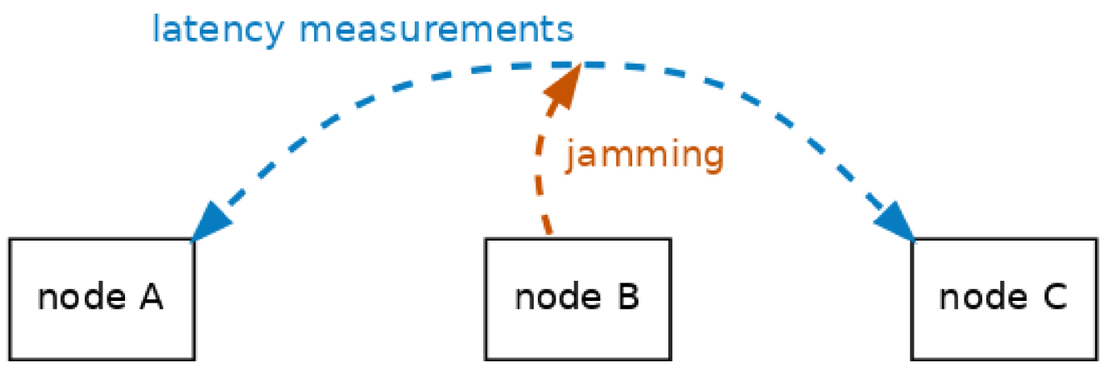
V2X (hence, Rail2X) uses specialized WiFi standard IEEE 802.11p

- pre-defined messages (e.g., emergency vehicle alert)
- focus on low latency (compared to, e.g., 802.11n)
- no access points (similar to ad-hoc mode)
- higher range (up to 1 km)

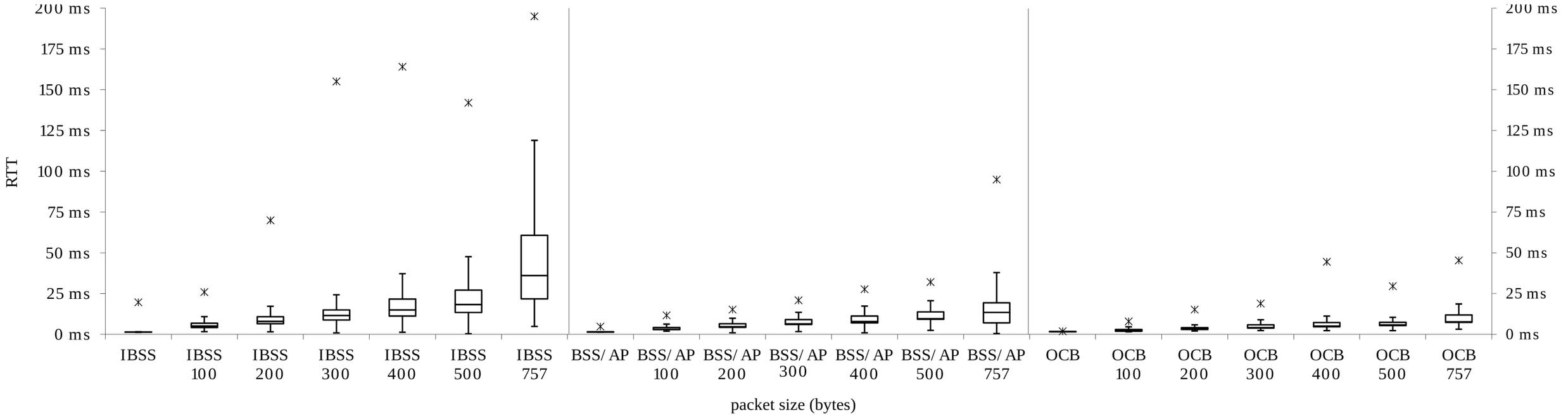
Rail2X in the IoT Lab







IEEE 802.11p packet round trip times while jamming



packet round trip times are lowest using IEEE 802.11p OCB mode

esp. with lowest standard deviation

desirable for soft real-time applications

Richter D, Pirl L, Beilharz J, Werling C, Polze A. Performance of Real-TimeWireless Communication for Railway Environments with IEEE 802.11p.

fault injection

experimental dependability assessment

- promises lower complexity
  - compared, e.g., to formal verification

fault injection ⊂ testing

try to prove the system wrong

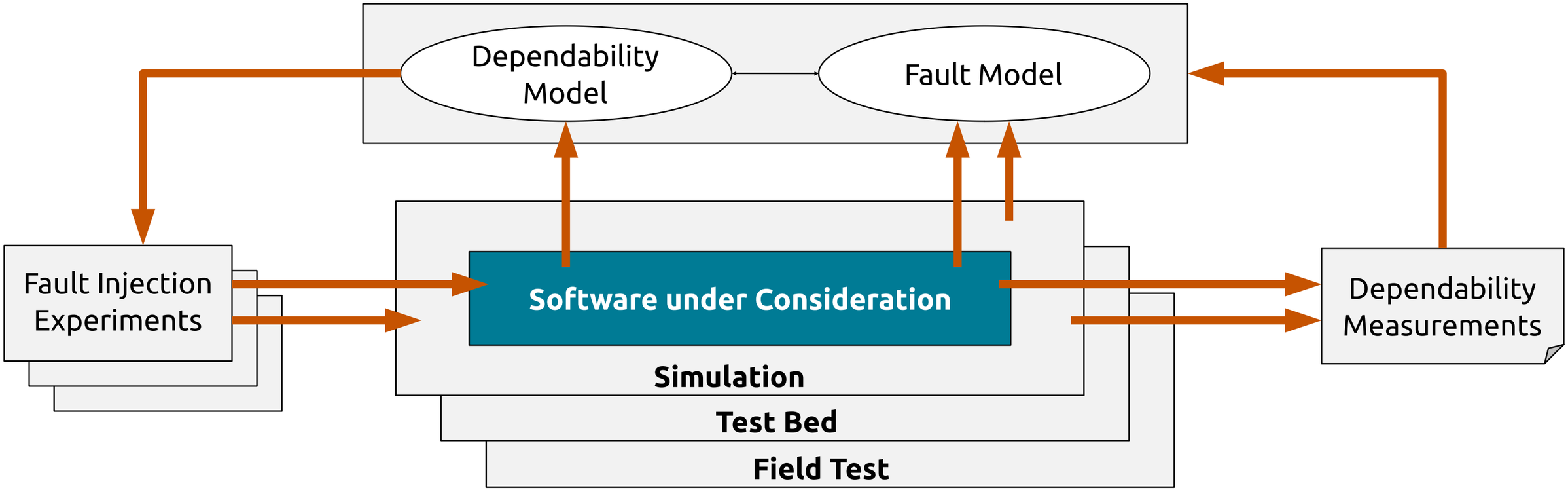
- instead of trying to prove the system correct as with “traditional” testing
- counter developers’ bias towards happy cases

concept

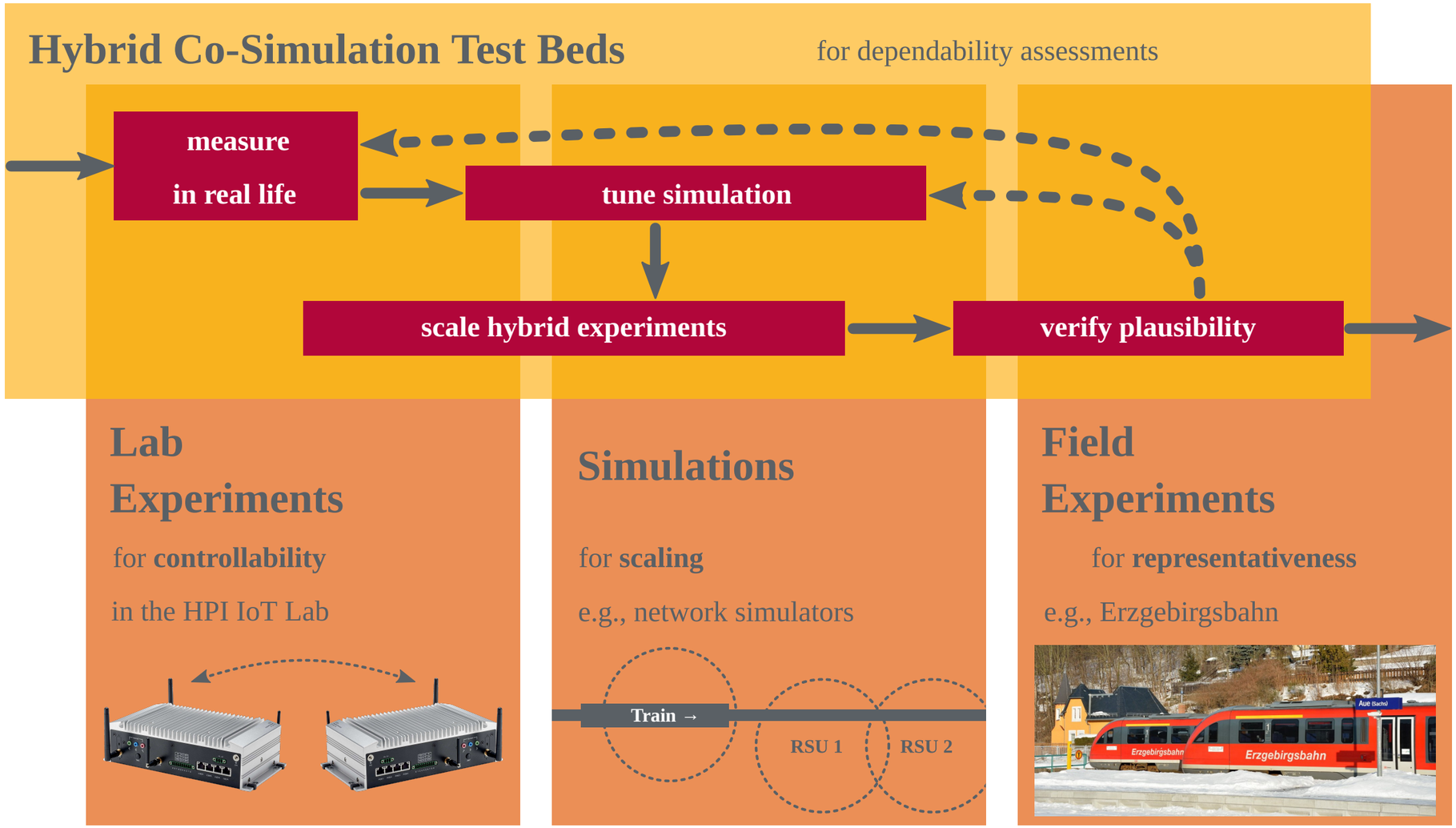
1. forcefully activate (“inject”) suspected error causes (“faults”)
2. assess delivered quality of service

development of methodologies

fault-injection-driven development



development of methodologies



hybrid testbeds & co-simulation

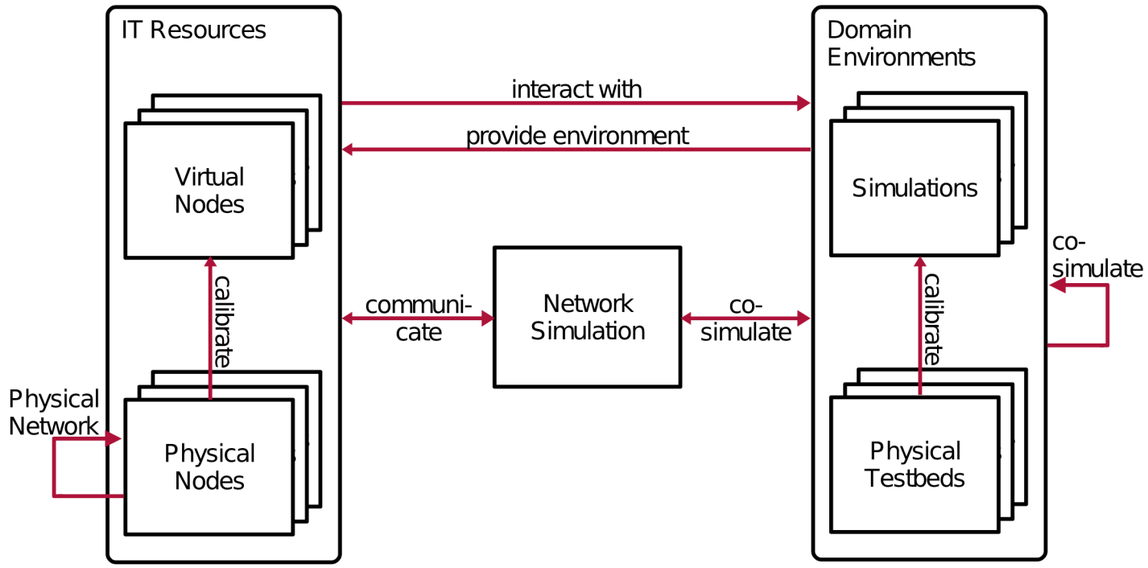
hybrid: software, hardware, and models “in-the-loop”

e.g., simulated wireless & physical wireless network

co-simulation: coupling of multiple domain-specific simulations

e.g., *SUMO* for traffic & *ns-3* for networking

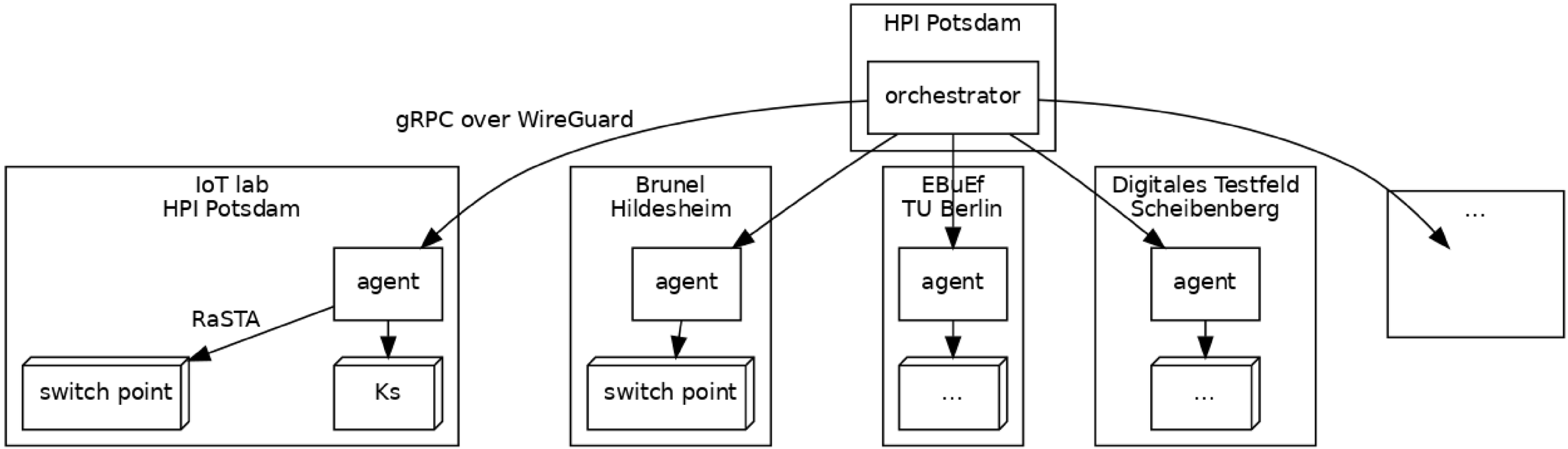
https://github.com/diselab/marvis



distributed testbeds

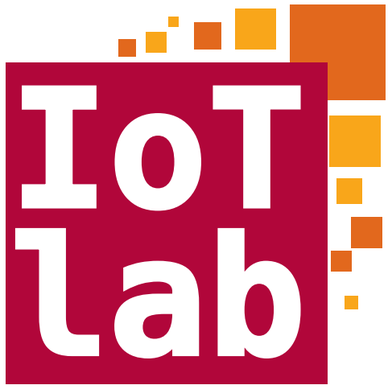
EULYNX live lab: distributed test environment

Kubernetes + Akri, generated interlocking software, automated tests, …



HPI IoT lab

… an environment for prototyping and assessments



building, DIY, testing, …

hybrid, co-simulated, and distributed setups

across/coupling of different domains

model-driven and -supported approaches

alternatives to specialized (test) hardware

hardware, software and model “in the loop”

dependability

(e.g., through fault injection)

Lukas Pirl

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Professorship for Operating Systems and Middleware

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